

INTRUDER 60 JR送信機 設定方法



最初に送信機の Swash type を 1 Servo NORM にして、電波をPPMに切替えます。

TYPE SELECT: HELI
SWASH TYPE: 1SERVO NORM
GYRO: POS 0: +50% POS 1: -50%

[REV SW]							[TRVL ADJ]						
THR	AIL	ELE	RUD	GER	PIT		THR	AIL	ELE	RUD	GER	PIT	
REV	REV	REV	NOR	REV	REV		100%	100%	100%	L120%	100%	100%	
							100%	100%	100%	R120%	100%	100%	

[THRO CURV] N			[THRO CURV] ST-1			[PIT CURV] N			[PIT CURV] ST-1		
POINT-	L	0%	POINT-	L	100%	POINT-	L	18%	POINT-	L	0%
	1	24%		1	90%		1	6%		1	24%
	2	50%		2	85%		2	56%		2	50%
	3	77%		3	90%		3	78%		3	76%
	H	100%		H	100%		H	100%		H	100%

INTRUDER 80V2 JR送信機 設定方法



最初に送信機の Swash type を 1 Servo NORM にして、電波をPPMに切替えます。

TYPE SELECT: HELI
SWASH TYPE: 1SERVO NORM
3/6軸切替え
DEVICE SEL: GEAR GEAR SW ACT

[REV SW]							[TRVL ADJ]						
THR	AIL	ELE	RUD	GER	PIT		THR	AIL	ELE	RUD	GER	PIT	
REV	REV	REV	NOR	REV	REV		100%	100%	100%	L120%	100%	100%	
							100%	100%	100%	R120%	100%	100%	

[THRO CURV] N			[THRO CURV] ST-1			[PIT CURV] N			[PIT CURV] ST-1		
POINT-	L	0%	POINT-	L	100%	POINT-	L	33%	POINT-	L	0%
	1	40%		1	84%		1	42%		1	1NH
	2	60%		2	80%		2	50%		2	50%
	3	80%		3	84%		3	75%		3	1NH
	H	100%		H	100%		H	100%		H	100%

INTRUDER 100S JR送信機 設定方法



最初に送信機の Swash type を 1 Servo NORM にして、電波をPPMに切替えます。

TYPE SELECT: HELI

SWASH TYPE: 1SERVO NORM

[REV SW]						
THR	AIL	ELE	RUD	GER	PIT	
REV	REV	REV	NOR	REV	REV	

[TRVL ADJ]						
THR	AIL	ELE	RUD	GER	PIT	
100%	80%	85%	L70%	100%	55%	
100%	80%	85%	R70%	100%	55%	

[THRO CURV] N			
POINT-	L	0%	
1	85%		
2	85%		
3	85%		
H	85%		

[THRO CURV] ST-1			
POINT-	L	95%	
1	95%		
2	95%		
3	95%		
H	95%		

[PIT CURV] N			
POINT-	L	35%	
1	45%		
2	50%		
3	75%		
H	100%		

[PIT CURV] ST-1			
POINT-	L	0%	
1	1NH		
2	50%		
3	1NH		
H	100%		

INTRUDER 60 FUTABA送信機 設定方法



最初に送信機の Swash type を 1 Servo NORM にして、電波をPPMに切替えます。

パラメーター

RESET: Execute

MODUL: PPM

TYPE: HELICOPTER

ATL: ON

SWASH: H-1

AUX-CH: SWB CH5を有効にし、SWを選びます。

[END POINT]		
1 AILE	100/100	
2 ELEV	100/100	
3 THRO	100/100	
4 RUDD	100/100	
5 GYRO	100/100	
6 PICH	100/100	

[REVERSE]		
AILE:		NOR
ELEV:		NOR
THRO:		NOR
RUDD:		REV
GYRO:		NOR
PICH:		NOR

[THR-CURV] (NORM)			
POINT-	1	0%	
2	25%		
3	37%		
4	50%		
5	62%		
6	75%		
7	100%		

[THR-CURV] (IDL)			
POINT-	1	100%	
2	95%		
3	90%		
4	88%		
5	90%		
6	95%		
7	100%		

[PIT CURV] (NORM)			
POINT-	1	-60%	
2	-36%		
3	-17%		
4	+8%		
5	+25%		
6	+50%		
7	+100%		

[PIT CURV] (IDL)			
POINT-	1	-100%	
2	-50%		
3	-25%		
4	0%		
5	+25%		
6	+50%		
7	+100%		

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パラメーター

RESET: Execute MODUL: PPM
TYPE: HELICOPTER ATL: ON
SWASH: H-1 AUX-CH: SWB CH5を有効にし、SWを選びます。

[END POINT]	
1 AILE	100/100
2 ELEV	100/100
3 THRO	100/100
4 RUDD	100/100
5 GYRO	100/100
6 PICH	100/100

[REVERSE]	
AILE:	NOR
ELEV:	NOR
THRO:	NOR
RUDD:	REV
GYRO:	NOR
PICH:	NOR

[THR-CURV] (NORM)	
POINT- 1	0%
2	25%
3	37%
4	50%
5	62%
6	75%
7	100%

[THR-CURV] (IDL)	
POINT- 1	100%
2	93%
3	90%
4	87%
5	90%
6	93%
7	100%

[PIT CURV] (NORM)	
POINT- 1	-32%
2	-20%
3	-12%
4	-5%
5	+25%
6	+50%
7	+100%

[PIT CURV] (IDL)	
POINT- 1	-100%
2	-50%
3	-25%
4	0%
5	+25%
6	+70%
7	+100%

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パラメーター

RESET: Execute MODUL: PPM
TYPE: HELICOPTER ATL: ON
SWASH: H-1 AUX-CH: SWB CH5を有効にし、SWを選びます。

[END POINT]	
1 AILE	85/85
2 ELEV	85/85
3 THRO	100/100
4 RUDD	70/70
5 GYRO	100/100
6 PICH	55/55

[REVERSE]	
AILE:	NOR
ELEV:	NOR
THRO:	NOR
RUDD:	REV
GYRO:	NOR
PICH:	NOR

[THR-CURV] (NORM)	
POINT- 1	0%
2	85%
3	85%
4	85%
5	85%
6	85%
7	85%

[THR-CURV] (IDL)	
POINT- 1	100%
2	95%
3	95%
4	95%
5	95%
6	95%
7	95%

[PIT CURV] (NORM)	
POINT- 1	-30%
2	-20%
3	-10%
4	0%
5	+25%
6	+50%
7	+100%

[PIT CURV] (IDL)	
POINT- 1	-100%
2	-50%
3	-25%
4	0%
5	+25%
6	+70%
7	+100%